







DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING
 Student Project Assessment and Review Committee
Mapping of CO with PO and PSO : AY 2017 - 18

Batch No	Title of the Project	CO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3	PSO4	Guide Name and Signature
EEE-B1	Underground cable fault detector robot	CO1	3	3	3	3	3	3	3	3	3		3	3	3				Dr MADHU PALATI <i>deh</i>
		CO2	2	2	2	2	2	2	2	2	2		2	2	2				
		CO3	3	3	3	3	3	3	3	3	3		3	3	3				
		CO4	3	3	3	3	3	3	3	3	3		3	3	3				
EEE-B2	VSC based DSTATCOM for power quality enhancement	CO1	3	2			3	2		2	3	3	3	3	3			3	VIKRAM CHEKURI
		CO2	3	2			3		2	2	3	3	3	3	3			3	
		CO3	3	3			3	3		2		3	3	3	3				
		CO4						3					3	3	3				
EEE-B3	Automated Cleaning And Cooling Technique For Solar Panel	CO1	3	3	3	3	3	3	3		3		3	3					MANJUN ATH BABU <i>ja</i>
		CO2	3	3	3	3	3	3	3		3		3	3					
		CO3	3	3	3	3	3	3	3		3		3	3					
		CO4																	
EEE-B4	MSP430 based low power control system for low	CO1	3	3				2	2	2	3	3		3				3	OZWIN DSOUZA <i>Or</i>
		CO2	3	3	3	3	3	3	2	2	2	3	3		3			3	

	orbit low power satellite	CO3	2	3	3	3	2	2	3	3	3	3				3	
		CO4				3			3	3	3	3	3				
EEE-B5	PERFORMANCE OPTIMIZATION OF AN EXISTING 50 MW GRID CONNECTED SOLAR PV POWER PLANT IN INDIA	CO1	2	3			2						3				SUMA UMESH
		CO2		3		3		3					3				
		CO3				2	3	3	2	2	2		2	1	3		
		CO4		1		2		2		3	3	3	3	2	2		
EEE-B6	HV fault detection and protection	CO1	2	3			2						1	3			PRASHANT A. ATHAVALE 
		CO2		3	2	2	1	2	2	2	2			1	2		
		CO3				3	3	2	2	1	3	3	1	2	3		
		CO4		2		3		2		3	3	3	3	2	2		
EEE-B7	Evaluating optimum path and executing planned path by mobile robot	CO1	3	3			2	2	2	3	3		3		3	3	Dr N. RAMARAO 
		CO2	3	3	3	3	3	2	2	2	3	3		3		3	
		CO3	2	2	3	3	3	2	2	3	3	3	3	3		3	
		CO4					3			3	3	3	3	3		3	
EEE-B8	Solar Power Cultivation using multilevel Inverter	CO1	3	3			2	3	2	3	2		3		3		SHILPA G 
		CO2	3	3	3	3	3	2	3	2	3	3	3	3		3	
		CO3				3	3	3	2	2	3	3	3	3		3	
		CO4				3	2			3	2	3	3	3		2	
EEE-B9	Solar powered automatic irrigation system	CO1	3	3			2	3	2	3	2		3		3		H. D. KATTIMANI 
		CO2	3	3	3	3	3	2	3	2	3	2		3		3	
		CO3				3	3	3	2	2	3	3	3	3		3	
		CO4				3	2			3	2	3	3	3		3	
EEE-B10	Speed control of DC motor using PID controller	CO1	3	3											3	3	NAGARA J CHONALI
		CO2				3	3	3							3	3	

